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<u>Space-time</u>		<u>Line-element</u>	<u>Chapter</u>
Alcubierre drive warp drive	$ds^2$	$= -dt^2 + [dx - V_s(t)f(r_s)dt]^2 + dy^2 + dz^2$	4
Classically anti-de-Sitter space-time	$ds^2$	$= -\cosh^2(r) dt^2 + dr^2 + \sinh^2(r) d\theta^2 + \sinh^2(r) \sin^2 \theta d\phi^2$	4
Cylindrical coordinates	$ds^2$	$= dr^2 + r^2 d\phi^2 + dz^2$	4

Einstein cylinder	$ds^2$	$= -dt^2 + (a_0)^2(d\theta^2 + \sin^2 \theta (d\phi^2 + \sin^2 \phi d\psi^2))$	9 (4), 13
Hyperbolsk plane – Poincaré Half plane	$ds^2$	$= \frac{1}{y^2}(dx^2 + dy^2)$	4,7
Rindler metric	$ds^2$	$= -X^2 dT^2 + dX^2$	2,3,4,7
Three-dimensional flat space-time in polar coordinates	$ds^2$	$= -dt^2 + dr^2 + r^2 d\phi^2$	4
Two-dimensional flat space	$dS^2$	$= dx^2 + dy^2$	4
Two-dimensional flat space-time	$ds^2$	$= -dt^2 + dx^2$	3,4
Worm hole geometry	$ds^2$	$= -dt^2 + dr^2 + (b^2 + r^2)(d\theta^2 + \sin^2 \theta d\phi^2)$	4

## 4 Christoffel Symbols, Geodesic Equations and Killing Vectors

### 4.1 Christoffel symbols.

#### 4.1.1 <sup>a</sup>Definitions

The Christoffel symbols of first kind<sup>1</sup>

$$\Gamma_{abc} = \frac{1}{2}(\partial_a g_{bc} + \partial_b g_{ca} - \partial_c g_{ab})$$

The Christoffel symbols of second kind<sup>2</sup>

$$\Gamma^a_{bc} = \frac{1}{2}g^{ad}(\partial_c g_{db} + \partial_b g_{dc} - \partial_d g_{bc})$$

The connection between the Christoffel symbols of the first and the second kind<sup>3</sup>

$$\Gamma^a_{bc} = g^{ad}\Gamma_{bcd}$$

#### 4.1.1.1 *Important remarks on the notation of the Christoffel symbols.*

We find that there are a variety of notations when introducing the Christoffel symbols, and we will state some of them here.

<sup>b</sup>Misner, Thorne, Wheeler

The Christoffel symbols of first kind<sup>4</sup>

$$\Gamma_{abc} = \frac{1}{2}(\partial_c g_{ba} + \partial_b g_{ac} - \partial_a g_{bc})$$

The Christoffel symbols of second kind<sup>5 6</sup>

$$\Gamma^a_{bc} = g^{ad}\Gamma_{dbc}$$

<sup>c</sup>D’Inverno

The Christoffel symbols of first kind<sup>7</sup>

$$\{ab, c\} = \frac{1}{2}(\partial_a g_{bc} + \partial_b g_{ca} - \partial_c g_{ab})$$

The Christoffel symbols of second kind<sup>8</sup>

$$\left\{ \begin{matrix} a \\ bc \end{matrix} \right\} = g^{ad}\{bc, d\}$$

<sup>1</sup> Symmetric in the first two indices:  $\Gamma_{abc} = \Gamma_{bac}$

<sup>2</sup> Symmetric in the last two indices:  $\Gamma^a_{bc} = \Gamma^a_{cb}$

<sup>3</sup> Notice: The third subscript is raised

<sup>4</sup> Symmetric in the last two indices:  $\Gamma_{abc} = \Gamma_{acb}$

<sup>5</sup> Symmetric in the last two indices:  $\Gamma^a_{bc} = \Gamma^a_{cb}$

<sup>6</sup> Notice: The first subscript is raised

<sup>7</sup> Symmetric in  $ab$

<sup>8</sup> Symmetric in  $bc$

## 4.1.2 Properties

$$\begin{aligned}\Gamma_{abc} &= \frac{1}{2}(\partial_a g_{bc} + \partial_b g_{ca} - \partial_c g_{ab}) = \frac{1}{2}(\partial_b g_{ac} + \partial_a g_{cb} - \partial_c g_{ba}) = \Gamma_{bac} \\ \Gamma_{aaa} &= \frac{1}{2}(\partial_a g_{aa} + \partial_a g_{aa} - \partial_a g_b) = \frac{1}{2}(\partial_a g_{aa}) \\ \Gamma_{aab} &= \frac{1}{2}(\partial_a g_{ab} + \partial_a g_{ba} - \partial_b g_{aa}) = \frac{1}{2}(2\partial_a g_{ab} - \partial_b g_{aa}) \\ \Gamma_{abb} &= \Gamma_{bab} = \frac{1}{2}(\partial_a g_{bb} + \partial_b g_{ba} - \partial_b g_{ab}) = \frac{1}{2}(\partial_a g_{bb}) \\ \Gamma_{abc} + \Gamma_{acb} &= \frac{1}{2}(\partial_a g_{bc} + \partial_b g_{ca} - \partial_c g_{ab}) + \frac{1}{2}(\partial_a g_{cb} + \partial_c g_{ba} - \partial_b g_{ac}) = \partial_a g_{bc} \\ \Gamma_{bc}^a &= \frac{1}{2}g^{ad}(\partial_c g_{db} + \partial_b g_{dc} - \partial_d g_{bc}) = \frac{1}{2}g^{ad}(\partial_b g_{dc} + \partial_c g_{db} - \partial_d g_{cb}) \\ &= \Gamma_{cb}^a \\ \Gamma_{aa}^a &= g^{ad}\Gamma_{daa} \\ \Gamma_{bb}^a &= g^{ad}\Gamma_{abd} \\ \Gamma_{ab}^a &= \Gamma_{ba}^a = g^{ad}\Gamma_{abd}\end{aligned}$$

## 4.1.3 The Christoffel Symbols of a diagonal metric in Three Dimensions

The line element

$$ds^2 = g_{xx}dx^2 + g_{yy}dy^2 + g_{zz}dz^2$$

The metric tensor and its inverse

$$g_{ab} = \begin{pmatrix} g_{xx} & & \\ & g_{yy} & \\ & & g_{zz} \end{pmatrix}$$

$$g^{ab} = \begin{pmatrix} \frac{1}{g_{xx}} & & \\ & \frac{1}{g_{yy}} & \\ & & \frac{1}{g_{zz}} \end{pmatrix}$$

The Christoffel symbols of first kind

$$\begin{aligned}\Gamma_{abc} &= \frac{1}{2}(\partial_a g_{bc} + \partial_b g_{ca} - \partial_c g_{ab}) \\ \Rightarrow \Gamma_{xyz} &= \Gamma_{xzy} = \Gamma_{yzx} = 0 \\ \Gamma_{aaa} &= \frac{1}{2}\partial_a g_{aa} \\ \Rightarrow \Gamma_{xxx} &= \frac{1}{2}\partial_x g_{xx} \\ \Gamma_{yyy} &= \frac{1}{2}\partial_y g_{yy} \\ \Gamma_{zzz} &= \frac{1}{2}\partial_z g_{zz} \\ \Gamma_{aab} &= \frac{1}{2}(2\partial_a g_{ab} - \partial_b g_{aa}) = -\frac{1}{2}\partial_b g_{aa} \\ \Rightarrow \Gamma_{xxy} &= -\frac{1}{2}\partial_y g_{xx}\end{aligned}$$

Christoffel symbols of the second kind

$$\begin{aligned}\Gamma_{bc}^a &= g^{ad}\Gamma_{bcd} \\ \Rightarrow \Gamma_{xy}^z &= \Gamma_{xz}^y = \Gamma_{yz}^x = 0 \\ \Gamma_{aa}^a &= g^{ad}\Gamma_{aad} \\ \Rightarrow \Gamma_{xx}^x &= g^{xx}\Gamma_{xxx} \\ \Rightarrow \Gamma_{yy}^y &= g^{yy}\Gamma_{yyy} \\ \Rightarrow \Gamma_{zz}^z &= g^{zz}\Gamma_{zzz} \\ \Gamma_{aa}^b &= g^{bd}\Gamma_{aad} \\ \Rightarrow \Gamma_{xx}^y &= g^{yy}\Gamma_{xxy}\end{aligned}$$

<sup>9</sup> Only sum over  $d$

<sup>10</sup> Only sum over  $d$

<sup>11</sup> Only sum over  $d$

$$\begin{aligned}
 \Gamma_{xxz} &= -\frac{1}{2}\partial_z g_{xx} & \Rightarrow \Gamma^z_{xx} &= g^{zz}\Gamma_{xxz} \\
 \Gamma_{yyx} &= -\frac{1}{2}\partial_x g_{yy} & \Rightarrow \Gamma^x_{yy} &= g^{xx}\Gamma_{yyx} \\
 \Gamma_{yyz} &= -\frac{1}{2}\partial_z g_{yy} & \Rightarrow \Gamma^z_{yy} &= g^{zz}\Gamma_{yyz} \\
 \Gamma_{zzx} &= -\frac{1}{2}\partial_x g_{zz} & \Rightarrow \Gamma^x_{zz} &= g^{xx}\Gamma_{zzx} \\
 \Gamma_{zzy} &= -\frac{1}{2}\partial_y g_{zz} & \Rightarrow \Gamma^y_{zz} &= g^{yy}\Gamma_{zzy} \\
 \Gamma_{abb} &= \Gamma_{bab} = \frac{1}{2}\partial_a g_{bb} & \Gamma^b_{ab} &= \Gamma^b_{ba} = {}^{12}g^{bd}\Gamma_{abd} \\
 \Rightarrow \Gamma_{xyy} &= \Gamma_{yyx} = \frac{1}{2}\partial_x g_{yy} & \Rightarrow \Gamma^y_{xy} &= \Gamma^y_{yx} = g^{yy}\Gamma_{xyy} \\
 \Gamma_{xzz} &= \Gamma_{zxx} = \frac{1}{2}\partial_x g_{zz} & \Rightarrow \Gamma^z_{xz} &= \Gamma^z_{zx} = g^{zz}\Gamma_{xzz} \\
 \Gamma_{yxx} &= \Gamma_{xyx} = \frac{1}{2}\partial_y g_{xx} & \Rightarrow \Gamma^x_{yx} &= \Gamma^x_{xy} = g^{xx}\Gamma_{yxx} \\
 \Gamma_{yzz} &= \Gamma_{zyz} = \frac{1}{2}\partial_y g_{zz} & \Rightarrow \Gamma^z_{yz} &= \Gamma^z_{zy} = g^{zz}\Gamma_{yzz} \\
 \Gamma_{zxx} &= \Gamma_{xzx} = \frac{1}{2}\partial_z g_{xx} & \Rightarrow \Gamma^x_{zx} &= \Gamma^x_{xz} = g^{xx}\Gamma_{zxx} \\
 \Gamma_{zyy} &= \Gamma_{yzy} = \frac{1}{2}\partial_z g_{yy} & \Rightarrow \Gamma^y_{zy} &= \Gamma^y_{yz} = g^{yy}\Gamma_{zyy}
 \end{aligned}$$

## 4.2 Cylindrical coordinates.

The line element:

$$ds^2 = dr^2 + r^2 d\phi^2 + dz^2$$

The metric tensor and its inverse:

$$g_{ab} = \begin{pmatrix} 1 & & \\ & r^2 & \\ & & 1 \end{pmatrix}$$

$$g^{ab} = \begin{pmatrix} 1 & & \\ & \frac{1}{r^2} & \\ & & 1 \end{pmatrix}$$

### 4.2.1 The non-zero Christoffel symbols

The Christoffel symbols of first kind

$$\Gamma_{abc} = \frac{1}{2}(\partial_a g_{bc} + \partial_b g_{ca} - \partial_c g_{ab})$$

$$\Gamma_{\phi\phi r} = -\frac{1}{2}\partial_r g_{\phi\phi} = -\frac{1}{2}\partial_r(r^2) = -r \quad \Rightarrow \Gamma^r_{\phi\phi} = g^{rr}\Gamma_{\phi\phi r} = -r$$

$$\Gamma_{r\phi\phi} = \Gamma_{\phi\phi r} = \frac{1}{2}\partial_r g_{\phi\phi} = \frac{1}{2}\partial_r(r^2) = r \quad \Rightarrow \Gamma^\phi_{r\phi} = \Gamma^\phi_{\phi r} = g^{\phi\phi}\Gamma_{r\phi\phi} = \frac{1}{r}$$

Christoffel symbols of the second kind

$$\Gamma^a_{bc} = g^{ad}\Gamma_{bcd}$$

### 4.2.2 The geodesic equation for cylindrical coordinates

<sup>13</sup>The geodesics equation:

$$\frac{d^2 x^a}{ds^2} + \Gamma^a_{bc} \frac{dx^b}{ds} \frac{dx^c}{ds} = 0$$

<sup>12</sup> Only sum over  $d$

<sup>13</sup> In this case we know the Christoffel symbols and want to find the geodesic equations

$$\begin{aligned}
 \underline{x^a = r:} \quad & \frac{d^2 r}{ds^2} + \Gamma^r_{bc} \frac{dx^b}{ds} \frac{dx^c}{ds} = 0 \\
 \Rightarrow & \frac{d^2 r}{ds^2} - r \left( \frac{d\phi}{ds} \right)^2 = 0 \\
 \underline{x^a = \phi:} \quad & \frac{d^2 \phi}{ds^2} + \Gamma^\phi_{bc} \frac{dx^b}{ds} \frac{dx^c}{ds} = 0 \\
 \Rightarrow & \frac{d^2 \phi}{ds^2} + \Gamma^\phi_{r\phi} \frac{dr}{ds} \frac{d\phi}{ds} + \Gamma^\phi_{\phi r} \frac{d\phi}{ds} \frac{dr}{ds} = 0 \\
 \Rightarrow & \frac{d^2 \phi}{ds^2} + \frac{2}{r} \frac{dr}{ds} \frac{d\phi}{ds} = 0 \\
 \underline{x^a = z:} \quad & \frac{d^2 z}{ds^2} + \Gamma^z_{bc} \frac{dx^b}{ds} \frac{dx^c}{ds} = 0 \\
 \Rightarrow & \frac{d^2 z}{ds^2} = 0
 \end{aligned}$$

#### 4.2.3 <sup>14</sup>The Christoffel symbols from the geodesic equations

We have

$$K = \frac{1}{2} g_{ab} \dot{x}^a \dot{x}^b = \frac{1}{2} (\dot{r})^2 + \frac{1}{2} r^2 (\dot{\phi})^2 + \frac{1}{2} (\dot{z})^2$$

Now we need

$$\begin{aligned}
 \underline{x^a = r:} \quad & \frac{\partial K}{\partial \dot{x}^a} = \frac{d}{ds} \left( \frac{\partial K}{\partial \dot{x}^a} \right) \\
 & \frac{\partial K}{\partial \dot{r}} = \frac{d}{ds} \left( \frac{\partial K}{\partial \dot{r}} \right) \\
 \Rightarrow & r \dot{\phi}^2 = \frac{d}{ds} (\dot{r}) = \ddot{r} \\
 \Rightarrow & 0 = \ddot{r} - r \dot{\phi}^2 \\
 \underline{x^a = \phi:} \quad & \frac{\partial K}{\partial \dot{\phi}} = \frac{d}{ds} \left( \frac{\partial K}{\partial \dot{\phi}} \right) \\
 & 0 = \frac{d}{ds} (r^2 \dot{\phi}) = 2r \dot{r} \dot{\phi} + r^2 \ddot{\phi} \\
 \Rightarrow & 0 = \ddot{\phi} + \frac{1}{r} \dot{r} \dot{\phi} + \frac{1}{r} \dot{\phi} \dot{r} \\
 \underline{x^a = z:} \quad & \frac{\partial K}{\partial \dot{z}} = \frac{d}{ds} \left( \frac{\partial K}{\partial \dot{z}} \right) \\
 \Rightarrow & 0 = \frac{d}{ds} (\dot{z}) = \ddot{z}
 \end{aligned}$$

Collecting the results

$$\begin{aligned}
 0 &= \ddot{r} - r \dot{\phi}^2 \\
 0 &= \ddot{\phi} + \frac{1}{r} \dot{r} \dot{\phi} + \frac{1}{r} \dot{\phi} \dot{r} \\
 0 &= \ddot{z}
 \end{aligned}$$

We can now find the Christoffel symbols from the geodesic equation:

$$\begin{aligned}
 \Gamma^r_{\phi\phi} &= -r \\
 \Gamma^\phi_{r\phi} &= \Gamma^\phi_{\phi r} = \frac{1}{r}
 \end{aligned}$$

<sup>14</sup> In this case we know the geodesic equations and want to find the Christoffel symbols

### 4.3 The plane in Cartesian coordinates

#### 4.3.1 Solve the geodesics equations of the plane in Cartesian coordinates.

We use the Euler-Lagrange method.

$$0 = \frac{d}{dS} \left( \frac{\partial F}{\partial \dot{x}^a} \right) - \frac{\partial F}{\partial x^a}$$

$$F = \frac{1}{2} g_{ab} \dot{x}^a \dot{x}^b$$

The line element

$$dS^2 = dx^2 + dy^2$$

$$F = \frac{1}{2} \dot{x}^2 + \frac{1}{2} \dot{y}^2$$

$$\underline{x^a = x:} \quad \frac{\partial F}{\partial x} = 0$$

$$\frac{\partial F}{\partial \dot{x}} = \dot{x}$$

$$\Rightarrow \quad \ddot{x} = 0$$

$$\underline{x^a = y:} \quad \frac{\partial F}{\partial y} = 0$$

$$\frac{\partial F}{\partial \dot{y}} = \dot{y}$$

$$\Rightarrow \quad \ddot{y} = 0$$

Collecting the results

$$\ddot{x} = 0$$

$$\ddot{y} = 0$$

The solution is obviously a straight line:

$$\ddot{x} = \frac{d^2 x}{dS^2} = 0$$

$$\Rightarrow \quad \dot{x} = \frac{dx}{dS} = k_0$$

$$\Rightarrow \quad x = k_0 S + k_1$$

$$\ddot{y} = \frac{d^2 y}{dS^2} = 0$$

$$\Rightarrow \quad \dot{y} = \frac{dy}{dS} = c_0$$

$$\Rightarrow \quad y = c_0 S + c_1 = c_0 \frac{(x - k_1)}{k_0} + c_1 = \frac{c_0}{k_0} x + c_1 - c_0 \frac{k_1}{k_0} = K_0 x + K_1$$

### 4.4 The Hyperbolic Plane

#### 4.4.1 Geodesics in the Hyperbolic Plane

The line element:

$$dS^2 = y^{-2} (dx^2 + dy^2) \quad y \geq 0$$

To find the geodesics we need a few integrals which we can solve:

a. Killing vector:

Because the metric is independent of  $x$  a Killing vector is

$$\xi = (\xi^x, \xi^y) = (1, 0)$$

$\xi \cdot \mathbf{u}$  is a conserved quantity along a geodesic, where

$$\mathbf{u} = (u^x, u^y) = \left( \frac{dx}{dS}, \frac{dy}{dS} \right)$$

$$\Rightarrow \quad \xi \cdot \mathbf{u} = \xi_a u^a = g_{ab} \xi^b u^a = g_{ax} \xi^x u^a = g_{xx} \xi^x u^x = y^{-2} u^x = K_1$$

$$\Rightarrow \frac{dx}{dS} = y^2 K_1 \tag{4.1.}$$

b. The line-element

$$dS^2 = y^{-2}(dx^2 + dy^2)$$

$$\Rightarrow 1 = y^{-2} \left( \left( \frac{dx}{dS} \right)^2 + \left( \frac{dy}{dS} \right)^2 \right) \tag{4.2.}$$

Substituting eq. (4.1.) into eq. (4.2.)

$$\Rightarrow 1 = y^{-2} \left( (y^2 K_1)^2 + \left( \frac{dy}{dS} \right)^2 \right)$$

$$\Rightarrow \left( \frac{dy}{dS} \right)^2 = y^2 K_1^2 \left( \frac{1}{K_1^2} - y^2 \right)$$

$$\Rightarrow \frac{dy}{dS} = \pm y K_1 \sqrt{\frac{1}{K_1^2} - y^2} \tag{4.3.}$$

Combining eq. (4.1.) and eq. (4.3.)

$$\Rightarrow \frac{dx}{dy} = \pm \frac{y}{\sqrt{\frac{1}{K_1^2} - y^2}}$$

$$\Rightarrow dx = \pm \frac{y dy}{\sqrt{\frac{1}{K_1^2} - y^2}}$$

$$\Rightarrow x - x_0 = \pm \int \frac{y dy}{\sqrt{\frac{1}{K_1^2} - y^2}} = {}^{15} \pm \sqrt{\frac{1}{K_1^2} - y^2}$$

$$\Rightarrow (x - x_0)^2 + y^2 = \frac{1}{K_1^2} \tag{y \geq 0}$$

If  $y = 0$  the geodesics are the vertical lines  $x = x_0 \pm \frac{1}{K_1}$ . If  $y > 0$  the geodesics are semicircles centered on the  $x$ -axis in  $(x_0, 0)$  with radius  $\frac{1}{K_1}$ .

$x$  and  $y$  as a function of  $S$ :

$$\begin{aligned} \frac{dy}{dS} &= \pm y K_1 \sqrt{\frac{1}{K_1^2} - y^2} \\ dS &= \pm \frac{dy}{y K_1 \sqrt{\frac{1}{K_1^2} - y^2}} \end{aligned}$$

<sup>15</sup> (Spiegel, 1990) (14.238)  $\int \frac{r dr}{\sqrt{a^2 - r^2}} = -\sqrt{a^2 - r^2}$

$$\begin{aligned} \Rightarrow S - S_0 &= \pm \int \frac{dy}{yK_1 \sqrt{\frac{1}{K_1^2} - y^2}} = {}^{16} \pm \ln \left( \frac{\frac{1}{K_1} + \sqrt{\frac{1}{K_1^2} - y^2}}{y} \right) \\ \Rightarrow \exp(\pm(S - S_0)) &= \frac{\frac{1}{K_1} + \sqrt{\frac{1}{K_1^2} - y^2}}{y} \\ \Rightarrow 0 &= \left( y \exp(\pm(S - S_0)) - \frac{1}{K_1} \right)^2 + y^2 - \frac{1}{K_1^2} \\ &= y^2 \exp(\pm 2(S - S_0)) - \frac{2y}{K_1} \exp(\pm(S - S_0)) + y^2 \\ &= y \left( y(1 + \exp(\pm 2(S - S_0))) - \frac{2}{K_1} \exp(\pm(S - S_0)) \right) \\ \Rightarrow y_1 &= 0 \\ y_2 &= \frac{2 \exp(S - S_0)}{K_1(1 + \exp(2(S - S_0)))} = {}^{17} \frac{1}{K_1 \cosh(S - S_0)} \\ y_3 &= \frac{2 \exp(-(S - S_0))}{K_1(1 + \exp(-2(S - S_0)))} = {}^{18} \frac{1}{K_1 \cosh(S - S_0)} = y_2 \\ \frac{dx}{dS} &= y^2 K_1 = \left( \frac{1}{K_1 \cosh(S - S_0)} \right)^2 K_1 = \frac{1}{K_1 \cosh^2(S - S_0)} \\ \Rightarrow x - x_0 &= \frac{1}{K_1} \int \frac{1}{\cosh^2(S - S_0)} dS = {}^{19} \frac{1}{K_1} \tanh(S - S_0) = \frac{1}{K_1} \tanh(S - S_0) \end{aligned}$$

Rescaling and collecting the results<sup>20</sup>

$$\begin{aligned} y &= \frac{1}{K_1 \cosh(S)} \\ x &= \frac{1}{K_1} \tanh(S) = y \sinh(S) \end{aligned}$$

#### 4.5 The Geodesic of two-dimensional Minkowski space-time

The line element:

$$\begin{aligned} ds^2 &= -dt^2 + dx^2 \\ \Rightarrow d\tau^2 &= {}^{21} dt^2 - ds^2 \end{aligned}$$

<sup>16</sup> (Spiegel, 1990) (14.241)  $\int \frac{dy}{y\sqrt{a^2-y^2}} = -\frac{1}{a} \ln \left( \frac{a+\sqrt{a^2-y^2}}{y} \right)$

<sup>17</sup>  $\frac{2e^x}{1+e^{2x}} = \frac{2e^x}{e^x(e^{-x}+e^x)} = \frac{2}{e^{-x}+e^x} = \frac{1}{\cosh x}$

<sup>18</sup>  $\frac{2e^{-x}}{1+e^{-2x}} = \frac{2e^{-x}}{e^{-x}(e^x+e^{-x})} = \frac{2}{e^{-x}+e^x} = \frac{1}{\cosh x}$

<sup>19</sup> (Spiegel, 1990) (14.571)  $\int \frac{1}{\cosh^2(x)} dx = \tanh x$

<sup>20</sup> Checking:  $1 = \frac{1}{y^2} \left( \left( \frac{dx}{dS} \right)^2 + \left( \frac{dy}{dS} \right)^2 \right) = K_1^2 \cosh^2(S) \left( \left( \frac{d\left(\frac{1}{K_1} \tanh(S)\right)}{dS} \right)^2 + \left( \frac{d\left(\frac{1}{K_1 \cosh(S)}\right)}{dS} \right)^2 \right) = \cosh^2 S \left( \left( \frac{1}{\cosh^2(S)} \right)^2 + \left( -\frac{1}{\cosh(S)} \tanh(S) \right)^2 \right) = \frac{1}{\cosh^2(S)} + \tanh^2(S) = 1$

<sup>21</sup> Negative time-signature i.e.  $d\tau^2 = -ds^2$ . See chapter 2

$$\Rightarrow 1 = \left(\frac{dt}{d\tau}\right)^2 - \left(\frac{dx}{d\tau}\right)^2$$

Killing vector: Because the metric is independent of  $t$  a Killing vector is

$$\xi = (\xi^t, \xi^x) = (1, 0)$$

$\xi \cdot \mathbf{u}$  is a conserved quantity along a geodesic, where

$$\mathbf{u} = (u^t, u^x) = \left(\frac{dt}{d\tau}, \frac{dx}{d\tau}\right)$$

$$\Rightarrow \xi \cdot \mathbf{u} = \xi_a u^a = g_{ab} \xi^b u^a = g_{tt} \xi^t u^t + g_{xx} \xi^x u^x = -\frac{dt}{d\tau}$$

$$\Rightarrow \frac{dt}{d\tau} = \text{constant} = K$$

Substituting this into the line element we find

$$1 = K^2 - \left(\frac{dx}{d\tau}\right)^2 = K^2 - \left(\frac{dt}{d\tau} \frac{dx}{dt}\right)^2 = K^2 - K^2 \left(\frac{dx}{dt}\right)^2$$

$$\Rightarrow \frac{dx}{dt} = \pm \sqrt{\frac{K^2 - 1}{K^2}} = \pm K'$$

When we solve this we find the familiar geodesics

$$x(t) = \pm K' t$$

Or

$$t(x) = \pm \frac{1}{K'} x$$

We can check whether these are timelike or spacelike and find the expected results

$$ds^2 = -dt^2 + dx^2 = \left(-1 + \left(\frac{dx}{dt}\right)^2\right) dt^2 = (-1 + (K')^2) dt^2$$

$$\begin{cases} < 0 \text{ timelike, if } K' < 1 \text{ inside the lightcone} \\ = 0 \text{ lightspeed, if } K' = 1 \text{ on the lightcone} \\ > 0 \text{ spacelike, if } K' > 1 \text{ outside the lightcone} \end{cases}$$

## 4.6 The Flat Space-time in two dimensions – <sup>22</sup>Rindler Space-time

### 4.6.1 <sup>h</sup>The time-like geodesic $X(T)$ of the Flat Space-time metric in two dimensions

To find  $X(T)$  we need a few integrals which we can solve:

a. The line element:

$$\begin{aligned} dS^2 &= -X^2 dT^2 + dX^2 \\ \Rightarrow d\tau^2 &= {}^{23} X^2 dT^2 - dX^2 \\ \Rightarrow 1 &= X^2 \left(\frac{dT}{d\tau}\right)^2 - \left(\frac{dX}{d\tau}\right)^2 \end{aligned} \quad (4.4.)$$

b. Killing vectors: Because the metric is independent of  $T$  a Killing vector is

$$\xi = (\xi^T, \xi^X) = (1, 0)$$

$\xi \cdot \mathbf{u}$  is a conserved quantity along a geodesic, where

$$\begin{aligned} \mathbf{u} &= (u^T, u^X) = \left(\frac{dT}{d\tau}, \frac{dX}{d\tau}\right) \\ \Rightarrow \xi \cdot \mathbf{u} &= \xi_a u^a = g_{ab} \xi^b u^a = g_{TT} \xi^T u^T + g_{XX} \xi^X u^X \\ &= -X^2 \cdot 1 \cdot \frac{dT}{d\tau} + 1 \cdot 0 \cdot \frac{dX}{d\tau} = -X^2 \frac{dT}{d\tau} \end{aligned}$$

<sup>22</sup> See chapter 2

<sup>23</sup> Negative time-signature i.e.  $d\tau^2 = -dS^2$ . See chapter 2

$$\Rightarrow X^2 \frac{dT}{d\tau} = \text{constant} = K \quad (4.5.)$$

Substituting eq. (4.5.) into eq. (4.4.)

$$1 = X^2 \left( \frac{K}{X^2} \right)^2 - \left( \frac{dX}{d\tau} \right)^2 = \frac{K^2}{X^2} - \left( \frac{dX}{d\tau} \right)^2$$

$$\Rightarrow \frac{dX}{d\tau} = {}^{24} \pm \sqrt{\frac{K^2}{X^2} - 1} \quad (4.6.)$$

If  $\frac{dX}{d\tau} > 0$ :

Dividing eq. (4.6.) by eq. (4.5.)

$$\Rightarrow \frac{\frac{dX}{d\tau}}{X^2 \frac{dT}{d\tau}} = \frac{\sqrt{\frac{K^2}{X^2} - 1}}{K}$$

$$\Rightarrow \frac{dX}{dT} = \frac{X^2}{K} \sqrt{\frac{K^2}{X^2} - 1} = \frac{X}{K} \sqrt{K^2 - X^2}$$

$$\Rightarrow dT = \frac{K}{X \sqrt{K^2 - X^2}} dX$$

$$\Rightarrow T - T^* = K \int \frac{dX}{X \sqrt{K^2 - X^2}} = {}^{25} {}^{26} - \ln \left( \frac{K + \sqrt{K^2 - X^2}}{X} \right)$$

Isolating  $X$

$$\left( \frac{K + \sqrt{K^2 - X^2}}{X} \right) = \exp(-(T - T^*))$$

$$\Rightarrow \sqrt{\left( \frac{K}{X} \right)^2 - 1} = \exp(-(T - T^*)) - \frac{K}{X}$$

$$\Rightarrow \left( \frac{K}{X} \right)^2 - 1 = \left( \exp(-(T - T^*)) - \frac{K}{X} \right)^2$$

$$= \exp(-2(T - T^*)) + \left( \frac{K}{X} \right)^2 - \frac{2K}{X} \exp(-(T - T^*))$$

$$\Rightarrow \frac{2K}{X} = \frac{\exp(-2(T - T^*)) + 1}{\exp(-(T - T^*))} = \exp(-(T - T^*)) + \exp(T - T^*)$$

$$= 2 \cosh(T - T^*)$$

And we find the geodesics

$$X(T) = {}^{27} \frac{K}{\cosh(T - T^*)}$$

#### 4.6.2 Are these geodesics space-like or time-like

$$dS^2 = -X^2 dT^2 + dX^2 = \left( -X^2 + \left( \frac{dX}{dT} \right)^2 \right) dT^2 = \left( -X^2 + \left( \frac{X}{K} \sqrt{K^2 - X^2} \right)^2 \right) dT^2$$

<sup>24</sup>  $K^2 > X^2$

<sup>25</sup>  $\int \frac{dx}{x\sqrt{a^2-x^2}} = -\frac{1}{a} \ln \left( \frac{a+\sqrt{a^2-x^2}}{x} \right)$  (Spiegel, 1990) (14.241)

<sup>26</sup>  $\left( \frac{K+\sqrt{K^2-X^2}}{X} \right) > 0$  if  $K > X$

<sup>27</sup> Notice: If  $\frac{dX}{d\tau} < 0$ :  $X(T) = \frac{K}{\cosh(T^*-T)} = \frac{K}{\cosh(T-T^*)}$

$$= -\frac{X^4}{K^2} dT^2 = -\frac{K^2}{\cosh^4(T - T^*)} dT^2 < 0$$

Which is inside the light-cone and these geodesics are time-like

#### 4.6.3 Is the world-line $X(T) = A \cosh(T)$ time-like or space-like:

$$\begin{aligned} dS^2 &= -X^2 dT^2 + dX^2 = \left(-X^2 + \left(\frac{dX}{dT}\right)^2\right) dT^2 = \left(-X^2 + \left(\frac{d(A \cosh T)}{dT}\right)^2\right) dT^2 \\ &= A^2(-\cosh^2 T + \sinh^2 T) dT^2 = -A^2 dT^2 < 0 \end{aligned}$$

Which is inside the light-cone and the world-line is time-like.

## 4.7 Three-dimensional flat space-time.

### 4.7.1 Null geodesics in three-dimensional flat space-time.

The line element:

$$\begin{aligned} ds^2 &= -dt^2 + dr^2 + r^2 d\phi^2 \\ d\tau^2 &= {}^{28}dt^2 - dr^2 - r^2 d\phi^2 \end{aligned}$$

To find the null-geodesics we need a few integrals which we can solve:

#### a. Killing vectors:

Because the metric is independent of  $t$  a Killing vector is

$$\xi = (\xi^t, \xi^r, \xi^\phi) = (1, 0, 0)$$

$\xi \cdot \mathbf{u}$  is a conserved quantity along a geodesic, where

$$\begin{aligned} \mathbf{u} &= (u^t, u^r, u^\phi) = \left(\frac{dt}{d\tau}, \frac{dr}{d\tau}, \frac{d\phi}{d\tau}\right) \\ \Rightarrow \xi \cdot \mathbf{u} &= \xi_a u^a = g_{ab} \xi^b u^a = g_{at} \xi^t u^a = g_{tt} \xi^t u^t + g_{rt} \xi^t u^r + g_{\phi t} \xi^t u^\phi \\ &= -u^t \\ \Rightarrow \frac{dt}{d\tau} &= K_1 \end{aligned} \tag{4.7.}$$

Because the metric is independent of  $\phi$  a Killing vector is

$$\begin{aligned} \zeta &= (\zeta^t, \zeta^r, \zeta^\phi) = (0, 0, 1) \\ \Rightarrow \zeta \cdot \mathbf{u} &= \zeta_a u^a = g_{ab} \zeta^b u^a = g_{a\phi} \zeta^\phi u^a \\ &= g_{t\phi} \zeta^\phi u^t + g_{r\phi} \zeta^\phi u^r + g_{\phi\phi} \zeta^\phi u^\phi = r^2 u^\phi \\ \Rightarrow r^2 \frac{d\phi}{d\tau} &= K_2 \end{aligned} \tag{4.8.}$$

#### b. Conservation of the four-velocity for a light ray

$$\begin{aligned} \mathbf{u} \cdot \mathbf{u} &= u_a u^a = g_{ab} u^b u^a = g_{tt} u^t u^t + g_{rr} u^r u^r + g_{\phi\phi} u^\phi u^\phi \\ &= \left(\frac{dt}{d\tau}\right)^2 - \left(\frac{dr}{d\tau}\right)^2 - r^2 \left(\frac{d\phi}{d\tau}\right)^2 = 0 \end{aligned} \tag{4.9.}$$

Substitute eq. (4.7.) and eq. (4.8.) into eq. (4.9.)

$$\begin{aligned} \Rightarrow 0 &= (K_1)^2 - \left(\frac{dr}{d\tau}\right)^2 - r^2 \left(\frac{K_2}{r^2}\right)^2 \\ \Rightarrow \left(\frac{dr}{d\tau}\right)^2 &= (K_1)^2 - \frac{1}{r^2} (K_2)^2 \\ \Rightarrow \frac{dr}{d\tau} &= \sqrt{(K_1)^2 - \frac{1}{r^2} (K_2)^2} \end{aligned} \tag{4.10.}$$

Combining eq. (4.7.) and eq. (4.10.)

<sup>28</sup> Negative time-signature i.e.  $d\tau^2 = -ds^2$ . See chapter 2

$$\begin{aligned}
 \Rightarrow \quad \frac{dr}{dt} &= \frac{1}{K_1} \sqrt{(K_1)^2 - \frac{1}{r^2} (K_2)^2} = \sqrt{1 - \frac{1}{r^2} \left(\frac{K_2}{K_1}\right)^2} \\
 &= \frac{dr}{\sqrt{1 - \frac{1}{r^2} \left(\frac{K_2}{K_1}\right)^2}} = \frac{r dr}{\sqrt{r^2 - \left(\frac{K_2}{K_1}\right)^2}} \\
 \Rightarrow \quad dt &= \int \frac{r dr}{\sqrt{r^2 - \left(\frac{K_2}{K_1}\right)^2}} = {}^{29} \sqrt{r^2 - \left(\frac{K_2}{K_1}\right)^2} \\
 \Rightarrow \quad t - t_0 &= \int \frac{r dr}{\sqrt{r^2 - \left(\frac{K_2}{K_1}\right)^2}} = {}^{29} \sqrt{r^2 - \left(\frac{K_2}{K_1}\right)^2} \tag{4.11.}
 \end{aligned}$$

Notice we can rewrite this into a hyperboloid.

$$\left(\frac{K_2}{K_1}\right)^2 = r^2 - (t - t_0)^2 \tag{4.12.}$$

Combining eq. (4.7.), eq. (4.8.) and eq. (4.11.)

$$\begin{aligned}
 \Rightarrow \quad r^2 \frac{d\phi}{dt} &= \frac{K_2}{K_1} \\
 \Rightarrow \quad \frac{d\phi}{dt} &= \frac{K_2}{K_1} \frac{1}{(t - t_0)^2 + \left(\frac{K_2}{K_1}\right)^2} \\
 \Rightarrow \quad \phi - \phi_0 &= \frac{K_2}{K_1} \int \frac{dt}{(t - t_0)^2 + \left(\frac{K_2}{K_1}\right)^2} = {}^{30} \tan^{-1} \left[ \frac{K_1}{K_2} (t - t_0) \right] \\
 \Rightarrow \quad t - t_0 &= \frac{K_2}{K_1} \tan(\phi - \phi_0) \tag{4.13.}
 \end{aligned}$$

Combining eq. (4.11.) and eq. (4.13.)

$$\begin{aligned}
 \Rightarrow \quad \sqrt{r^2 - \left(\frac{K_2}{K_1}\right)^2} &= \frac{K_2}{K_1} \tan(\phi - \phi_0) \\
 \Rightarrow \quad r &= \pm \frac{K_2}{K_1} \sqrt{\tan^2(\phi - \phi_0) + 1} \tag{4.14.}
 \end{aligned}$$

Collecting the results we find the null-geodesics:

$$\left(\frac{K_2}{K_1}\right)^2 = r^2 - (t - t_0)^2 \tag{4.12.}$$

$$t - t_0 = \frac{K_2}{K_1} \tan(\phi - \phi_0) \tag{4.13.}$$

$$r = \pm \frac{K_2}{K_1} \sqrt{\tan^2(\phi - \phi_0) + 1} \tag{4.14.}$$

Light rays moves on straight lines in curved space. From our point of view the tip of the light cone  $(t, r)$  moves along a hyperbolic path eq. (4.14.).

<sup>29</sup> (Spiegel, 1990) (14.210)  $\int \frac{r dr}{\sqrt{r^2 - a^2}} = \sqrt{r^2 - a^2}$

<sup>30</sup> (Spiegel, 1990) (14.125)  $\int \frac{dt}{t^2 + a^2} = \frac{1}{a} \tan^{-1} \frac{t}{a}$

## 4.8 The worm-hole geometry

### 4.8.1 Volume in the Wormhole geometry

The three-dimensional volume on a  $t = \text{constant}$  slice of the wormhole geometry bounded by two spheres of coordinate radius  $R$  on each side of the throat.

The line-element

$$ds^2 = -dt^2 + dr^2 + (b^2 + r^2)(d\theta^2 + \sin^2 \theta d\phi^2)$$

$$d\tau^2 = {}^{31}dt^2 - dr^2 - (b^2 + r^2)(d\theta^2 + \sin^2 \theta d\phi^2)$$

The volume

$$\begin{aligned} V &= \int dl^1 \int dl^2 \int dl^3 = \int_{-R}^R (b^2 + r^2) dr \int_0^\pi \sin \theta d\theta \int_0^{2\pi} d\phi = 4\pi \int_{-R}^R (b^2 + r^2) dr \\ &= 4\pi \left[ rb^2 + \frac{1}{3}r^3 \right]_{-R}^R = 4\pi \left( \left( Rb^2 + \frac{1}{3}R^3 \right) - \left( (-R)b^2 + \frac{1}{3}(-R)^3 \right) \right) \\ &= \frac{4\pi}{3} * 2R * (3b^2 + R^2) \end{aligned}$$

### 4.8.2 Geodesic Equations in a Wormhole Geometry

We use the Euler-Lagrange method.

$$0 = \frac{d}{ds} \left( \frac{\partial F}{\partial \dot{x}^a} \right) - \frac{\partial F}{\partial x^a}$$

$$F = \frac{1}{2} g_{ab} \dot{x}^a \dot{x}^b$$

The line element

$$ds^2 = -dt^2 + dr^2 + (b^2 + r^2)(d\theta^2 + \sin^2 \theta d\phi^2)$$

$$\Rightarrow F = -\frac{1}{2}\dot{t}^2 + \frac{1}{2}\dot{r}^2 + \frac{1}{2}(b^2 + r^2)\dot{\theta}^2 + \frac{1}{2}(b^2 + r^2)\sin^2 \theta \dot{\phi}^2$$

$$\underline{x^a = t:} \quad \frac{\partial F}{\partial t} = 0$$

$$\frac{\partial F}{\partial \dot{t}} = -\dot{t}$$

$$\Rightarrow \dot{t} = 0$$

$$\underline{x^a = r:} \quad \frac{\partial F}{\partial r} = r(\dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2)$$

$$\frac{\partial F}{\partial \dot{r}} = \dot{r}$$

$$\Rightarrow \ddot{r} = r\dot{\theta}^2 + r\sin^2 \theta \dot{\phi}^2$$

$$\underline{x^a = \theta:} \quad \frac{\partial F}{\partial \theta} = (b^2 + r^2) \sin \theta \cos \theta \dot{\phi}^2$$

$$\frac{\partial F}{\partial \dot{\theta}} = (b^2 + r^2)\dot{\theta}$$

$$\frac{d}{ds} \left( \frac{\partial F}{\partial \dot{\theta}} \right) = 2r\dot{r}\dot{\theta} + (b^2 + r^2)\ddot{\theta}$$

$$\Rightarrow \ddot{\theta} = \sin \theta \cos \theta \dot{\phi}^2 - \frac{2r}{(b^2 + r^2)} \dot{r}\dot{\theta}$$

$$\underline{x^a = \phi:} \quad \frac{\partial F}{\partial \phi} = 0$$

$$\frac{\partial F}{\partial \dot{\phi}} = (b^2 + r^2) \sin^2 \theta \dot{\phi}$$

<sup>31</sup> Negative time-signature i.e.  $d\tau^2 = -ds^2$ . See chapter 2

$$\begin{aligned} \Rightarrow 0 &= \frac{d}{ds} \left( (b^2 + r^2) \sin^2 \theta \dot{\phi} \right) \\ &= 2r \sin^2 \theta \dot{r} \dot{\phi} + 2(b^2 + r^2) \sin \theta \cos \theta \dot{\theta} \dot{\phi} + (b^2 + r^2) \sin^2 \theta \ddot{\phi} \\ \Rightarrow \ddot{\phi} &= -\frac{2r}{(b^2 + r^2)} \dot{r} \dot{\phi} - 2 \cot \theta \dot{\theta} \dot{\phi} \end{aligned}$$

Collecting the results

$$\begin{aligned} \ddot{t} &= 0 \\ \ddot{r} &= r\dot{\theta}^2 + r \sin^2 \theta \dot{\phi}^2 \\ \ddot{\theta} &= \sin \theta \cos \theta \dot{\phi}^2 - \frac{2r}{(b^2 + r^2)} \dot{r} \dot{\theta} \\ \ddot{\phi} &= -\frac{2r}{(b^2 + r^2)} \dot{r} \dot{\phi} - 2 \cot \theta \dot{\theta} \dot{\phi} \end{aligned}$$

The non-zero Christoffel symbols are

$$\begin{aligned} \Gamma^r_{\theta\theta} &= -r & \Gamma^r_{\phi\phi} &= -r \sin^2 \theta \\ \Gamma^\theta_{\phi\phi} &= -\sin \theta \cos \theta & \Gamma^\theta_{r\theta} &= \Gamma^\theta_{\theta r} = \frac{r}{(b^2 + r^2)} \\ \Gamma^\phi_{r\phi} &= \Gamma^\phi_{\phi r} = \frac{r}{(b^2 + r^2)} & \Gamma^\phi_{\theta\phi} &= \Gamma^\phi_{\phi\theta} = \cot \theta \end{aligned}$$

### 4.8.3 The travel time through a wormhole

Use the geodesic equations to calculate the proper travel time of an astronaut travelling through a wormhole throat along the coordinate radius  $r$  from  $r = R$  to  $r = -R$ . The initial radial four-velocity is  $u^r \equiv U$ , and because of spherical symmetry  $u^\theta = u^\phi = 0$

The four-velocity is

$$u^a = (u^t, u^r, u^\theta, u^\phi) = \left( \frac{dt}{d\tau}, \frac{dr}{d\tau}, \frac{d\theta}{d\tau}, \frac{d\phi}{d\tau} \right) = {}^{32} \left( \sqrt{1 + U^2}, U, 0, 0 \right)$$

we will only look at  $u^r$ . We use the geodesic equation

$$\ddot{r} = r\dot{\theta}^2 + r \sin^2 \theta \dot{\phi}^2$$

which we can rewrite

$$\begin{aligned} \frac{d^2 r}{d\tau^2} &= r\dot{\theta}^2 + r \sin^2 \theta \dot{\phi}^2 = 0 \\ \Rightarrow \frac{d^2 r}{d\tau^2} &= \frac{d}{d\tau} \left( \frac{dr}{d\tau} \right) = \frac{du^r}{d\tau} = 0 \end{aligned}$$

which implies that  $u^r = U$  is a constant along the astronaut's world-line. So we can solve

$$\begin{aligned} u^r &= \frac{dr}{d\tau} = U \\ \Rightarrow d\tau &= \frac{1}{U} dr \\ \Rightarrow \Delta\tau &= \int_{-R}^R \frac{1}{U} dr = \frac{1}{U} [r]_{-R}^R = \frac{1}{U} (R - (-R)) = \frac{2R}{U} \end{aligned}$$

So the travel time through the wormhole  $\Delta\tau = \frac{2R}{U}$  is very much alike the usual time/speed calculation: distance=time\*velocity except with the velocity replaced by the four velocity.

#### 4.8.3.1 Is the trajectory time-like or space-like?

The line-element<sup>33</sup>

<sup>32</sup>  $u^t$  is found from the fact that the  $u^a u_a = -1$  is a conserved quantity:  $u^a u_a = u^a \eta_{ij} u^a = -(u^t)^2 + (u^r)^2 + (u^\theta)^2 + (u^\phi)^2 = -(u^t)^2 + U^2 = -1 \Rightarrow u^t = \sqrt{1 + U^2}$ , where  $1 + U^2 > 0$

<sup>33</sup> If we instead used the line-element  $ds^2 = -dt^2 + dr^2 + (b^2 + r^2)(d\theta^2 + \sin^2 \theta d\phi^2)$  we would find  $dt^2 \left( \frac{1}{1+U^2} \right) < 0$ , which is time-like.

$$\begin{aligned}
d\tau^2 &= dt^2 - dr^2 - (b^2 + r^2)(d\theta^2 + \sin^2\theta d\phi^2) \\
&= dt^2\left(1 - \left(\frac{dr}{dt}\right)^2 - (b^2 + r^2)\left(\left(\frac{d\theta}{dt}\right)^2 + \sin^2\theta\left(\frac{d\phi}{dt}\right)^2\right)\right) \\
&= {}^{34}dt^2\left(1 - \left(\frac{dr}{dt}\frac{d\tau}{dt}\right)^2 - (b^2 + r^2)((0)^2 + \sin^2\theta(0)^2)\right) = dt^2\left(1 - \left(U \cdot \frac{1}{\sqrt{1+U^2}}\right)^2\right) \\
&= dt^2\left(\frac{1+U^2-U^2}{1+U^2}\right) = dt^2\left(\frac{1}{1+U^2}\right) > 0
\end{aligned}$$

i.e. the trajectory is time-like.

#### 4.9 Warp space-time – The Alcubierre Drive

The line-element

$$\begin{aligned}
ds^2 &= -dt^2 + [dx - V_s(t)f(r_s)dt]^2 + dy^2 + dz^2 \\
\Rightarrow d\tau^2 &= {}^{35}dt^2 - [dx - V_s(t)f(r_s)dt]^2 - dy^2 - dz^2 \\
&= (1 - V_s(t)^2 f(r_s)^2)dt^2 + 2V_s(t)f(r_s)dxdt - dx^2 - dy^2 - dz^2
\end{aligned}$$

Notice: The line-element is dependent on the velocity of the spaceship  $V_s(t)$ . If the velocity is zero the line-element reduces to flat Minkowsky space-time.

The metric

$$g_{ab} = \begin{pmatrix} -1 + V_s(t)^2 f(r_s)^2 & -V_s(t)f(r_s) & 0 & 0 \\ -V_s(t)f(r_s) & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Where  $V_s(t) \equiv \frac{dx_s(t)}{dt}$ ,  $r_s^2 \equiv [(x - x_s(t))^2 + y^2 + z^2]$  and  $f(r_s)$  is a smooth positive <sup>36</sup>function that satisfies  $f(0) = 1$  and decreases away from the origin to vanish for  $r_s \gg R$  for some  $R$ .

The trajectory

A spaceship travels along a curve

$$(t, x, y, z) = (t, x_s(t), 0, 0)$$

With the four-velocity

$$u = (u^t, u^x, u^y, u^z) = \left(\frac{dt}{d\tau}, \frac{dx_s(t)}{d\tau}, 0, 0\right)$$

Manipulating the line element we get

$$\begin{aligned}
d\tau^2 &= dt^2 - [dx - V_s(t)f(r_s)dt]^2 - dy^2 - dz^2 \\
&= \left(1 - \left[\frac{dx}{dt} - V_s(t)f(r_s)\right]^2 - \left(\frac{dy}{dt}\right)^2 - \left(\frac{dz}{dt}\right)^2\right) dt^2 \\
&= \left(1 - \left[\frac{dx_s(t)}{dt} - V_s(t)f(r_s)\right]^2\right) dt^2 \\
&= (1 - [1 - f(r_s)]^2 V_s(t)^2) dt^2 > 0
\end{aligned}$$

Which means the trajectory is time-like and at every point along the curve

$$(t, x, y, z) = (t, x_s(t), 0, 0)$$

the four-velocity of the spaceship lies inside the light cone if  $V_s(t)^2 < 1$ , i.e. smaller than the velocity of light.

<sup>34</sup> Because all the differentials with respect to  $\theta$  and  $\phi$  are zero, we can use the chain rule in this simple manner.

<sup>35</sup> Negative time-signature i.e.  $d\tau^2 = -ds^2$ . See chapter 2

<sup>36</sup>  $f(r_s) = \frac{\tanh(\sigma(r_s+R)) - \tanh(\sigma(r_s-R))}{2 \tanh(\sigma R)}$  with arbitrary parameters  $R > 0$  and  $\sigma > 0$

4.9.1 Ship time and coordinate time.

Imagine a spaceship traveling between two space-stations. What is the spaceship proper time  $\Delta\tau$  compared to the coordinate time  $t = \Delta T$ .

The line element

$$d\tau^2 = dt^2 - [dx - V_s(t)f(r_s)dt]^2 - dy^2 - dz^2$$

$$\Rightarrow \left(\frac{d\tau}{dt}\right)^2 = 1 - \left[\frac{dx}{dt} - V_s(t)f(r_s)\right]^2 - \left(\frac{dy}{dt}\right)^2 - \left(\frac{dz}{dt}\right)^2$$

The ship moves on a curve in the  $(x, y)$ -plane with the coordinates  $(t, x_s(t), 0, 0)$

$$\Rightarrow \left(\frac{d\tau}{dt}\right)^2 = 1 - \left[\frac{dx_s(t)}{dt} - V_s(t)f(r_s)\right]^2 = 1 - [V_s(t) - V_s(t)f(r_s)]^2$$

$$= 1 - V_s(t)^2[1 - f(r_s)]^2$$

$$d\tau = \sqrt{1 - V_s(t)^2[1 - f(r_s)]^2} dt$$

If we assume the spaceship has a constant velocity  $V_s(t)^2 = V_s(0)^2$

$$\Rightarrow \Delta\tau = \sqrt{1 - V_s(0)^2[1 - f(r_s)]^2} \Delta T$$

In detail

$$\Delta T \rightarrow \begin{cases} \Delta\tau & \text{if } r_s \rightarrow 0, f(0) = 1 & (i) \\ \frac{\Delta\tau}{\sqrt{1 - V_s(0)^2[1 - f(r_s)]^2}} \gg \Delta\tau & \text{if } 0 < r_s < R & (ii) \\ \frac{\Delta\tau}{\sqrt{1 - V_s(0)^2}} > \Delta\tau & \text{if } r_s \gg R, f(r_s) = 0 & (iii) \end{cases}$$

where (ii) corresponds to the warp period and (iii) to the Minkowski space-time

On the light cone,  $d\tau^2 = 0$ :

The line-element is depending on the velocity of the space ship  $V_s(t)$ . This has a rather peculiar effect.

$$0 = -dt^2 + [dx - V_s(t)f(r_s)dt]^2 = \left(-1 + \left[\frac{dx}{dt} - V_s(t)f(r_s)\right]^2\right) dt^2$$

$$\Rightarrow \frac{dx}{dt} = \pm 1 + V_s(t)f(r_s)$$

Now, as you can see there are areas where  $\frac{dx}{dt}$  is larger than one. This means that from our point of view, there are areas where the spaceship seems to move with a velocity larger than the speed of light. There is no contradiction here though, because locally the velocity of the spaceship  $V_s(t)$  is smaller than the speed of light.

4.10 <sup>P</sup>Classic Anti-de Sitter Spacetime

4.10.1 Classic Anti-de Sitter Space-time is conformally related to the Einstein cylinder

The line element

$$ds^2 = -\cosh^2(r) dt^2 + dr^2 + \sinh^2(r) d\theta^2 + \sinh^2(r) \sin^2 \theta d\phi^2$$

We use the transformation

$$\cosh(r) = \frac{1}{\cos \psi}$$

$$\Rightarrow \sinh^2(r) = \frac{1}{\cos^2 \psi} - 1 = \tan^2 \psi$$

$$d(\cosh(r)) = d\left(\frac{1}{\cos \psi}\right)$$

$$\sinh(r) dr = \frac{\sin \psi}{\cos^2 \psi} d\psi$$

$$\begin{aligned} \Rightarrow dr^2 &= \frac{\sin^2 \psi}{\sinh^2(r) \cos^4 \psi} d\psi^2 = \frac{1}{\cos^2 \psi} d\psi^2 \\ \Rightarrow ds^2 &= -\frac{1}{\cos^2 \psi} dt^2 + \frac{1}{\cos^2 \psi} d\psi^2 + \tan^2 \psi d\theta^2 + \tan^2 \psi \sin^2 \theta d\phi^2 \\ &= \frac{1}{\cos^2 \psi} (-dt^2 + d\psi^2 + \sin^2 \psi d\theta^2 + \sin^2 \psi \sin^2 \theta d\phi^2) \\ &= \frac{1}{\cos^2 \psi} (-dt^2 + d\psi^2 + \sin^2 \psi (d\theta^2 + \sin^2 \theta d\phi^2)) \end{aligned}$$

Which is conformally related to the Einstein cylinder

$$ds^2 = -dt^2 + (a_0)^2 (d\theta^2 + \sin^2 \theta (d\phi^2 + \sin^2 \phi d\psi^2))$$

#### 4.10.2 The Path of a light ray – the null geodesics in the Classic Anti de Sitter space-time

To find the null-geodesics we need some integrals which we can solve:

##### a. Killing vectors:

Because the metric is independent of  $t$  a Killing vector is

$$\xi = (\xi^t, \xi^r, \xi^\theta, \xi^\phi) = (1, 0, 0, 0)$$

$\xi \cdot \mathbf{u}$  is a conserved quantity along a geodesic, where

$$\begin{aligned} \mathbf{u} &= (u^t, u^r, u^\theta, u^\phi) = \left( \frac{dt}{ds}, \frac{dr}{ds}, \frac{d\theta}{ds}, \frac{d\phi}{ds} \right) \\ \Rightarrow \xi \cdot \mathbf{u} &= \xi_a u^a = g_{ab} \xi^b u^a = g_{at} \xi^t u^a \\ &= g_{tt} \xi^t u^t + g_{rt} \xi^t u^r + g_{\theta t} \xi^t u^\theta + g_{\phi t} \xi^t u^\phi = -\cosh^2(r) \dot{t} \\ \Rightarrow \dot{t} &= \frac{K_1}{\cosh^2(r)} \end{aligned} \quad (4.15.)$$

Because the metric is independent of  $\phi$  a Killing vector is

$$\begin{aligned} \zeta &= (\zeta^t, \zeta^r, \zeta^\theta, \zeta^\phi) = (0, 0, 0, 1) \\ \Rightarrow \zeta \cdot \mathbf{u} &= \zeta_a u^a = g_{ab} \zeta^b u^a = g_{a\phi} \zeta^\phi u^a \\ &= g_{t\phi} \zeta^\phi u^t + g_{r\phi} \zeta^\phi u^r + g_{\theta\phi} \zeta^\phi u^\theta + g_{\phi\phi} \zeta^\phi u^\phi \\ &= \sinh^2(r) \sin^2 \theta u^\phi \\ \Rightarrow \dot{\phi} &= \frac{K_2}{\sinh^2(r) \sin^2 \theta} \end{aligned} \quad (4.16.)$$

##### b. Conservation of the four-velocity for a light ray

$$\begin{aligned} \mathbf{u} \cdot \mathbf{u} &= u_a u^a = g_{ab} u^b u^a \\ &= g_{tt} u^t u^t + g_{rr} u^r u^r + g_{\theta\theta} u^\theta u^\theta + g_{\phi\phi} u^\phi u^\phi \\ &= -\cosh^2(r) \dot{t}^2 + \dot{r}^2 + \sinh^2(r) \dot{\theta}^2 + \sinh^2(r) \sin^2 \theta \dot{\phi}^2 = 0 \\ \Rightarrow 0 &= -\cosh^2(r) \dot{t}^2 + \dot{r}^2 + \sinh^2(r) \dot{\theta}^2 + \sinh^2(r) \sin^2 \theta \dot{\phi}^2 \end{aligned} \quad (4.17.)$$

##### c. The geodesic equations.

We use the Euler-Lagrange method.

$$\begin{aligned} 0 &= \frac{d}{ds} \left( \frac{\partial F}{\partial \dot{x}^a} \right) - \frac{\partial F}{\partial x^a} \\ F &= \frac{1}{2} g_{ab} \dot{x}^a \dot{x}^b \\ &= -\frac{1}{2} \cosh^2(r) \dot{t}^2 + \frac{1}{2} \dot{r}^2 + \frac{1}{2} \sinh^2(r) \dot{\theta}^2 + \frac{1}{2} \sinh^2(r) \sin^2 \theta \dot{\phi}^2 \\ \underline{x^a = t}: \quad \frac{\partial F}{\partial t} &= 0 \\ \frac{\partial F}{\partial \dot{t}} &= -\cosh^2(r) \dot{t} \\ \frac{d}{ds} \left( \frac{\partial F}{\partial \dot{t}} \right) &= -\cosh^2(r) \ddot{t} - 2 \sinh(r) \dot{t} \dot{r} \\ \Rightarrow 0 &= \cosh^2(r) \ddot{t} + 2 \sinh(r) \dot{t} \dot{r} \end{aligned} \quad (4.18.)$$

$$\begin{aligned}
 \underline{x^a = r:} \quad & \frac{\partial F}{\partial r} = -\sinh(r) \dot{t}^2 + \cosh(r) \dot{\theta}^2 + \cosh(r) \sin^2 \theta \dot{\phi}^2 \\
 & \frac{\partial F}{\partial \dot{r}} = \dot{r} \\
 & \frac{d}{ds} \left( \frac{\partial F}{\partial \dot{r}} \right) = \ddot{r} \\
 \Rightarrow \quad & 0 = \ddot{r} + \sinh(r) \dot{t}^2 - \cosh(r) \dot{\theta}^2 - \cosh(r) \sin^2 \theta \dot{\phi}^2 \tag{4.19.}
 \end{aligned}$$

$$\begin{aligned}
 \underline{x^a = \theta:} \quad & \frac{\partial F}{\partial \theta} = \sinh^2(r) \cos \theta \dot{\phi}^2 \\
 & \frac{\partial F}{\partial \dot{\theta}} = \sinh^2(r) \dot{\theta} \\
 & \frac{d}{ds} \left( \frac{\partial F}{\partial \dot{\theta}} \right) = 2 \cosh(r) \dot{r} \dot{\theta} + \sinh^2(r) \ddot{\theta} \\
 \Rightarrow \quad & 0 = 2 \cosh(r) \dot{r} \dot{\theta} + \sinh^2(r) \ddot{\theta} - \sinh^2(r) \cos \theta \dot{\phi}^2 \tag{4.20.}
 \end{aligned}$$

$$\begin{aligned}
 \underline{x^a = \phi:} \quad & \frac{\partial F}{\partial \phi} = 0 \\
 & \frac{\partial F}{\partial \dot{\phi}} = \sinh^2(r) \sin^2 \theta \dot{\phi} \\
 & \frac{d}{ds} \left( \frac{\partial F}{\partial \dot{\phi}} \right) = 2 \cosh(r) \sin^2 \theta \dot{\phi} + 2 \sinh^2(r) \cos \theta \dot{\phi} + \sinh^2(r) \sin^2 \theta \ddot{\phi} \\
 \Rightarrow \quad & 0 = 2 \cosh(r) \sin^2 \theta \dot{\phi} + 2 \sinh^2(r) \cos \theta \dot{\phi} + \sinh^2(r) \sin^2 \theta \ddot{\phi} \tag{4.21.}
 \end{aligned}$$

Collecting the results

$$\dot{t} = \frac{K_1}{\cosh^2(r)} \tag{4.15.}$$

$$\dot{\phi} = \frac{K_2}{\sinh^2(r) \sin^2 \theta} \tag{4.16.}$$

$$0 = -\cosh^2(r) \dot{t}^2 + \dot{r}^2 + \sinh^2(r) \dot{\theta}^2 + \sinh^2(r) \sin^2 \theta \dot{\phi}^2 \tag{4.17.}$$

$$0 = \cosh^2(r) \ddot{t} + 2 \sinh(r) \dot{t} \dot{r} \tag{4.18.}$$

$$0 = \ddot{r} + \sinh(r) \dot{t}^2 - \cosh(r) \dot{\theta}^2 - \cosh(r) \sin^2 \theta \dot{\phi}^2 \tag{4.19.}$$

$$0 = 2 \cosh(r) \dot{r} \dot{\theta} + \sinh^2(r) \ddot{\theta} - \sinh^2(r) \cos \theta \dot{\phi}^2 \tag{4.20.}$$

$$0 = 2 \cosh(r) \sin^2 \theta \dot{\phi} + 2 \sinh^2(r) \cos \theta \dot{\phi} + \sinh^2(r) \sin^2 \theta \ddot{\phi} \tag{4.21.}$$

The coordinates  $t$  and  $r$ :

We need

$$\ddot{t} = -\frac{2 \sinh(r) \cosh(r)}{\cosh^4(r)} K_1 \tag{4.22.}$$

Substituting eq. (4.15.) and eq. (4.22.) into eq. (4.18.)

$$\Rightarrow \quad 0 = \cosh^2(r) \left( -\frac{2 \sinh(r) \cosh(r)}{\cosh^4(r)} K_1 \right) + 2 \sinh(r) \left( \frac{K_1}{\cosh^2(r)} \right) \dot{r}$$

$$\Rightarrow \quad 0 = -\cosh(r) + \dot{r}$$

$$\Rightarrow \quad \dot{r} = \cosh(r) \tag{4.23.}$$

Dividing eq. (4.15.) with eq. (4.23.)

$$\begin{aligned}
 \frac{\dot{t}}{\dot{r}} &= \frac{dt}{dr} = \frac{K_1}{\cosh^3(r)} \\
 \Rightarrow \quad \int_{t_0}^t dt &= \int_{r_0}^r \frac{K_1}{\cosh^3(r)} dr
 \end{aligned}$$

$$\begin{aligned} \Rightarrow \quad t - t_0 &= {}^{37} \left[ \frac{\sinh(r)}{2 \cosh^2(r)} \right]_{r_0}^r + \frac{1}{2} \int_{r_0}^r \frac{dr}{\cosh(r)} = {}^{38} \left[ \frac{\sinh(r)}{2 \cosh^2(r)} + \tan^{-1}(e^r) \right]_{r_0}^r \\ &= \frac{\sinh(r)}{2 \cosh^2(r)} + \tan^{-1}(e^r) - \left( \frac{\sinh(r_0)}{2 \cosh^2(r_0)} + \tan^{-1}(e^{r_0}) \right) \\ &= \begin{cases} \frac{\sinh(r)}{2 \cosh^2(r)} + \tan^{-1}(e^r) - K_3 \text{ if } r_0 \rightarrow 0 \\ \rightarrow K_4 \text{ if } r \rightarrow \infty \end{cases} \end{aligned}$$

Interpreting this means, that no matter how far the light travels in this spacetime from  $r = 0$  to  $r \rightarrow \infty$  this happens within a limited time<sup>39</sup>.

As an exercise we will look at the other coordinates as well.

The coordinates  $r$  and  $\theta$  :

We need

$$\begin{aligned} \ddot{\phi} &= -2K_2 \left( \frac{2 \cosh(r) \sinh(r)}{\sinh^4(r) \sin^2 \theta} \dot{r} + \frac{\cos \theta \sin \theta}{\sinh^2(r) \sin^4 \theta} \dot{\theta} \right) \\ &= -2K_2 \left( \frac{2 \cosh(r) \sinh(r)}{\sinh^4(r) \sin^2 \theta} \cosh(r) + \frac{\cos \theta \sin \theta}{\sinh^2(r) \sin^4 \theta} \dot{\theta} \right) \end{aligned} \quad (4.24.)$$

Manipulate eq. (4.23.) and substitute eq. (4.16.) and eq. (4.24.)

$$\begin{aligned} 0 &= 2 \cosh(r) \sin^2 \theta \dot{\phi} + 2 \sinh^2(r) \cos \theta \dot{\phi} + \sinh^2(r) \sin^2 \theta \ddot{\phi} \\ &= {}^{40} 2K_2 \left[ \frac{\cosh(r)}{\sinh^2(r)} + \frac{\cos \theta}{\sin^2 \theta} - \frac{\cosh^2(r)}{\sinh(r)} - \frac{\cos \theta}{\sin \theta} \dot{\theta} \right] \\ \Rightarrow \quad \dot{\theta} &= \frac{\cosh(r) \tan \theta}{\sinh^2(r)} + \frac{1}{\sin \theta} - \frac{\cosh^2(r) \tan \theta}{\sinh(r)} \end{aligned} \quad (4.25.)$$

Dividing (IX) with (VIII):

$$\frac{\dot{\theta}}{\dot{r}} = \frac{d\theta}{dr} = \frac{\tan \theta}{\sinh^2(r)} + \frac{1}{\cosh(r) \sin \theta} - \frac{\tan \theta}{\tanh(r)}$$

This illustrates how difficult it is to solve the geodesic equations in GR.

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<sup>37</sup>  $\int \frac{dr}{\cosh^n(r)} = \frac{\sinh(r)}{(n-1) \cosh^{n-1}(r)} + \frac{(n-2)}{(n-1)} \int \frac{dr}{\cosh^{n-2}(r)}$  (14.588) (Spiegel, 1990)

<sup>38</sup>  $\int \frac{dr}{\cosh(r)} = 2 \tan^{-1}(e^r)$  (14.567) (Spiegel, 1990)

<sup>39</sup> Notice: We haven't used eq. (III) so this result also valid for an object with mass.

<sup>40</sup>  $= 2 \cosh(r) \sin^2 \theta \frac{K_2}{\sinh^2(r) \sin^2 \theta} + 2 \sinh^2(r) \cos \theta \frac{K_2}{\sinh^2(r) \sin^2 \theta} + \sinh^2(r) \sin^2 \theta \left[ -2K_2 \left( \frac{2 \cosh(r) \sinh(r)}{\sinh^4(r) \sin^2 \theta} \cosh(r) + \frac{\cos \theta \sin \theta}{\sinh^2(r) \sin^4 \theta} \dot{\theta} \right) \right] =$

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<sup>a</sup> (McMahon, 2006, s. 72-73), (Kay, 1988, s. 68-70, 74-75)

<sup>b</sup> (Charles Misner, 2017, s. 314)

<sup>c</sup> (d'Inverno, 1992, p. 83)

<sup>d</sup> (McMahon, 2006, s. 324), (Kay, 1988, s. 68-70, 74-75)

<sup>e</sup> (McMahon, 2006, s. 83)

<sup>f</sup> (Hartle, 2003, p. 183)

<sup>g</sup> (Penrose, 2004, s. 50), (Hartle, Gravity - An introduction to Einstein's General Relativity, 2003, p. 184)

<sup>h</sup> (McMahon, 2006, s. 84), (Hartle, An Introduction to Einstein's General Relativity, 2003, s. 143, 165, 184), (Kay, 1988, s. 126)

<sup>i</sup> (Hartle, 2003, p. 143)

<sup>j</sup> (Hartle, 2003, p. 184)

<sup>k</sup> (Hartle, 2003, p. 166)

<sup>l</sup> (Hartle, 2003, p. 172)

<sup>m</sup> (Hartle, 2003, p. 174)

<sup>n</sup> (Hartle, 2003, p. 175)

<sup>o</sup> [https://en.wikipedia.org/wiki/Alcubierre\\_drive](https://en.wikipedia.org/wiki/Alcubierre_drive), (Hartle, 2003, pp. 144, 166)

<sup>p</sup> (Choquet-Bruhat, 2015, s. 97)